

Imprimitive groups:

- $g \triangleright \Omega$ transitively

Defn:

let $\mathcal{B} = \{B_1, \dots, B_n\}$ $B_i \subset \Omega$; $B_i \cap B_j = \emptyset$ for $i \neq j$
 $\cup B_i = \Omega$ (i.e. \mathcal{B} is a partition of Ω).

\mathcal{B} is a block system for $g \triangleright \Omega$ when

$$B_i^g \in \mathcal{B} \quad \forall g \in G$$

(i.e. \mathcal{B} is G -invariant).

Ex: trivial block systems: $\mathcal{B}_1 = \{\{i\} : i \in \Omega\}$

$$\mathcal{B}_\infty = \{\Omega\}.$$

Ex: $G = \langle (1, 2, 3, 4) \rangle$

$$\mathcal{B} = \{\{1, 3\}, \{2, 4\}\}$$

Defn: We say that $g \triangleright \Omega$ imprimitively iff $g \triangleright$ transitively and admits a non-trivial block system.

(Otherwise we say that $g \triangleright$ primitively).

Lemma: Let $B = \{B_1, \dots, B_n\}$ be a block system for $G \curvearrowright \Omega$. The action of G on blocks is transitive.

Proof: transitive $\Leftrightarrow \forall 1 \leq i, j \leq n \exists g \in G$ s.t. $B_i^g = B_j$.

Let $\delta \in B_i$ and $\gamma \in B_j$. since $G \curvearrowright \Omega$ transitively
 $\Rightarrow \exists g \in G$ s.t. $\delta^g = \gamma$. the same g moves B_i to B_j .

Corollary:

- $|\Omega| = |B| \cdot |B_i|$
- Block system is determined by a single block.
- If $|G| = p^{\text{prime}}$; $G \curvearrowright \Omega$ transitively, then $G \curvearrowright$ primitively.

Lemma: Suppose $G \curvearrowright \Omega$ transitively and let $S = \text{stab}_G(x)$ for some $x \in \Omega$.

then there is a bijection between subgroups

$$\{T : S \leq T \leq G\} \text{ and}$$

block systems $B = \{B_1, \dots, B_n\}$ for $G \curvearrowright \Omega$.

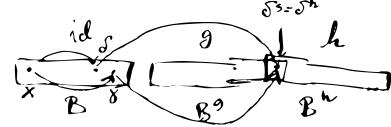
The bijection is given by

$$x, T \rightsquigarrow x^T =: B_1 \text{ and } B = B_1^S.$$

The inverse is simply

$$B = \{B_1, \dots, B_n\} \rightsquigarrow \text{Stab}_G(B_1).$$

Proof:

Let $S \leq T \leq G$ and pick $x \in \Omega$. 

Set $B = x^T$, $\mathcal{B} = B^g$.

Claim: \mathcal{B} is a block system for $G \cap \Omega$.

Let $B^g \cap B^h \neq \emptyset$ i.e. $g^h = x^t$ for some $t \in T$.

Since $B = x^T \Rightarrow g = x^a$, $h = x^b$ for some $a, b \in T$.

$$\Rightarrow x^{ag} = x^{bh} \text{ i.e. } x^{ag \cdot h^{-1} \cdot b} = x$$

$$\Rightarrow ag \cdot h^{-1} \cdot b \in \text{Stab}_G(x) \leq T$$

$$\Rightarrow gh^{-1} \in T.$$

Since T stabilizes B $B^{gh^{-1}} \cap B = B$ i.e. $B^g = B^h$

G -invariance is obvious by the definition of \mathcal{B}

Let \mathcal{B} be a block system, $x \in B, \in \mathcal{B}$.

If g fixes x , $\Rightarrow x \in B_1 \cap B_1^g \neq \emptyset \Rightarrow B_1^g = B_1$

$$\text{Stab}_G(x) \leq \text{Stab}_G(B_1).$$

Let $\delta \in B_1 \Rightarrow x^\delta = x$ (by transitivity) $\Rightarrow \delta \in B_1^g \cap B_1 \neq \emptyset$
 $\Rightarrow g \in \text{Stab}_G(\delta)$. Therefore $x^{\text{Stab}_G(B_1)} = B_1$.

To make that the maps are inverse of each other we need to check:

$$\text{Stab}_G(x^{\text{Stab}_G(B_1)}) = ? \quad \text{Stab}_G(B_1) = :T.$$

If $g \in G$ s.t. $(x^T)^g \Rightarrow \forall t \in T \exists l \in T$ s.t. $x^{tg} = x^t$

$$\Rightarrow x^{tgt^{-1}} = x \Rightarrow tgt^{-1} \in T \Rightarrow g \in T.$$

□

Definition:

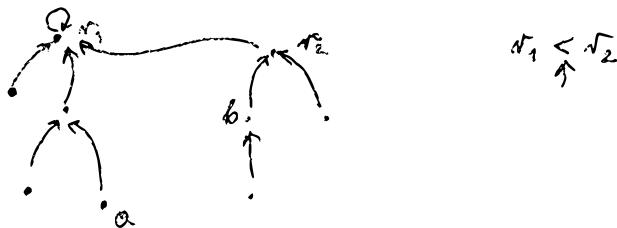
A subgroup $S \leq G$ is called maximal if $S \neq G$ and there is no subgroup $T \leq G$ s.t. $S \neq T$.

Corollary:

- A transitive group G is primitive iff a point stabilizer is a maximal subgroup.
 - Subgroup $S \leq G$ is maximal iff $G \cap S \backslash G$ is primitive.
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Finding blocks:

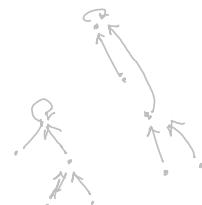
- Let $X \subset \Omega$ be a subset (a seed) we want to be $\subset B_1$.
- Start with $B_X = X, \{B_y = \{y\} \text{ for } y \in \Omega \setminus X\}$
- Act via $G = \langle S \rangle$ on each of B_i and merge those which intersect.
- Each B_i is represented by a unique element \rightarrow the representative
- for each $x \in \Omega$ we store the representative of B_i which x belongs to.



ALGORITHM: Union!

Input: C_1 - a subset of Ω
 C_2 - a subset of Ω

Output: the union of C_1 and C_2



begin

$r_1 = \text{representative}(G)$

r_2 = representative (c_2)

if $r_1 \neq r_2$

set-representative! (r_2, r_1)

End

return C₁

encl

ALGORITHM: Block System

INPUT:

- S - a generating set for $G = \langle S \rangle$
- Ω - a set with G -action
- B - a subset of Ω

Output: B - the finest Block system for $\mathcal{G} \cap \Omega$
 s.t. $B \subset B_1$

begin

for $x \in \Omega$
 \setminus set-representative! (x, x)

Encl

queue = [] # a queue of points that have changed

for $x \in B$

set-representative!(x, first(B))

push! (queue, x)

end

initialize
the initial
partition

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while !isempty (queue)
    x = pop! (queue)
    y = representative (x)
    for s ∈ S
        α = representative (xs)
        β = representative (ys)
        if α ≠ β
            Union! (α, β)
            push β to queue
        end
    end
end
return r
end

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Theorem:

The algorithm converges to a block system
for Ω

Proof: Since we're taking only unions
the returned partition contains B in one of its
blocks.

Since every Union! moves up on the
lattice of all partitions of Ω and
 $\{\Omega\}$ - the trivial block system is the
maximal element the algorithm has to stop.

We need to prove that the refined partition \mathcal{B} is g -invariant i.e. $\forall B \in \mathcal{B} \quad \forall x, y \in B \quad \forall g \in S \quad x^g, y^g \in B^g \in \mathcal{B}$.

- Observe:
- It's enough to check this for $y = r(x)$
 - It's enough to check this for $g \in S$.

$$\forall B \in \mathcal{B} \quad \forall x \in B \quad \forall s \in S \quad r(x^s) = r((rx)^s).$$

$$\forall x \in Q \quad \forall s \in S \quad r(x^s) = r(r(x)^s). \quad (*)$$

- It's enough to enforce the condition only for pts which changed label \rightarrow it's the queue.

Had we added all points whose representative is β we would be ok. But only β was added...

Let $x \in Q$: $\text{representative}(x) = \beta \neq x$

$\Rightarrow x$ was on the queue

$\Rightarrow (*)$ is satisfied for (x, β) .

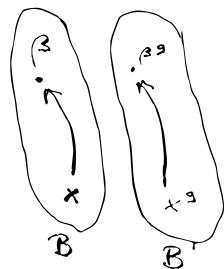
If it happens that we change

$r(\beta) = \alpha$ then $(*)$ is enforced

for (β, α) , so $r(x^s) = r(\beta^s) =$

$$= r(r(\beta)^s) = r(\alpha^s) \quad \square.$$

=



Lemma: Let $1 \in B_1 \in \mathcal{B}$ \leftarrow block system for $Q \setminus \Omega$.

B_1 is union of orbits of $\text{Stab}_S(1)$.

Proof: If $g \in \text{Stab}_S(1)$, $1 \neq \alpha \in B_1 \Rightarrow$

$$\{1, \alpha\}^g = \{1, \alpha^g\} \subset B_1^g = B_1 \Rightarrow \alpha^{g \in \text{Stab}_S(1)} \in B_1.$$

Corollary: Any block that contains $\{1, \alpha\}$
contains also $\{1\} \cup {}^{\alpha} \text{Stab}_{\alpha}(1)$.

Practical tip: We don't need to know $\text{Stab}_{\alpha}(1)$ exactly!

It's enough to find a few random elements from $\text{stab}_{\alpha}(1)$ to compute the orbit of α .
(e.g. Schreier generators from the transversal.)

Recall: Every intransitive group is a subdirect product of its transitive parts.

Is there a universal description for imprimitive groups?

Defn: Let G, H be groups. let $\psi: H \rightarrow \text{Aut}(G)$ be a homomorphism. Then

$G \rtimes_{\psi} H = \langle (g, h) \in G \times H, \cdot_{\psi}, (1, 1) \rangle$
is a group with

$$(g, h) \cdot_{\psi} (a, b) = (g \cdot \psi(h)(a), h \cdot b)$$

$$(1, 1) = (g, h) \cdot (a, b) \Rightarrow b = h^{-1}, a = \psi(h)(g^{-1})$$

Note: $G \triangleleft G \rtimes_{\psi} H$.