## SAut*(F*5*)* **has property (T)**

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## **Outline**

*ñ* **Group Laplacians & Property (T)** *ñ* **Positivity & SDP The procedure** *ñ* **Concrete examples**

 $\rho$  *G* =  $\langle S | R \rangle$  is a finitely presented group generated by a fixed **symmetric generating set** (i.e. *S* <sup>−</sup><sup>1</sup> = *S*).

### <span id="page-3-0"></span>**[Group Laplacians](#page-3-0)**

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- *<sup>ñ</sup>* spectrum of <sup>∆</sup> is real and non-negative;
- $\blacktriangleright$  the second eigenvalue  $\lambda_1$  is called the **spectral gap**

$$
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The **Kazhdan's constant**  $\kappa(G, S)$  is defined as

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over all orthogonal representations *π* of *G*. We say that *G* has the **Kazhdan's property (T)** if and only if there exists a (finite) generating set *S* such that  $\kappa(G, S) > 0$ .

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- $\rho$  Provide a constructive (computable) proof for  $n = 5$ .

Random group elements in finite groups:

#### **Theorem (Lubotzky & Pak, 2000)**

*Let K be a* finite group generated by  $k \le n$  elements. If  $SAut(F_n)$  has *property (T) with constant*  $\kappa = \kappa(SAut(F_n), \{transvectors\}) > 0$ , then **PRA** *walk on*  $\Gamma_n = \Gamma_n(K)$  *has fast mixing rate, i.e.* 

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\left|\left|Q_{(g)}^t-U\right|\right|_{\text{tv}}\leqslant \epsilon \qquad \text{for} \qquad t\geqslant \frac{16}{\kappa^2}\log\frac{|\Gamma_n|}{\epsilon}\sim O\left(\left(\frac{n}{\kappa}\right)^2\log\frac{|\mathcal{K}|}{\epsilon}\right)
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#### **Note**

We do observe fast mixing rate in practice for large *n*.

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### **Corollary**

*Let*  $G = \langle S | ... \rangle$  *be a finitely generated group. If there exists*  $\lambda > 0$  *such that* <sup>∆</sup><sup>2</sup> <sup>−</sup> *<sup>λ</sup>*<sup>∆</sup> *<sup>á</sup>* <sup>0</sup>*, then <sup>G</sup> has property (T) with*

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# **How to prove that**  $\Delta^2 - \lambda \Delta \ge 0$ ?

## How to prove that a polynomial  $f \ge 0$ ?

### <span id="page-32-0"></span>**POSITIVITY & SDP**

### **Theorem (Hilbert's Positivstellensatz, 1888)**

*An everywhere non-negative polynomial <sup>p</sup>* <sup>∈</sup> <sup>Σ</sup> <sup>2</sup>R*[x*1*, . . . , xn] (is a sum of squares) if and only if either*

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**Example (Motzkin, 1970s)**

*x*<sup>4</sup>y<sup>2</sup> + *x*<sup>2</sup>y<sup>2</sup> − 3*x*<sup>2</sup>y<sup>2</sup> + 1 ≥ 0 but not SOS.

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### **Theorem (Artin, 1924)**

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p \geq 0 \iff \exists q: q^2p \in \Sigma^2 \mathbb{R}[x_1,\ldots,x_n]
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By evaluating

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f(x,y) = (1, x, y) \begin{bmatrix} p_{11} & p_{12} & p_{13} \ p_{21} & p_{22} & p_{23} \ p_{31} & p_{32} & p_{33} \end{bmatrix} \begin{pmatrix} 1 \ x \ y \end{pmatrix}
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since then  $P = Q^TQ$  and (for  $(1, x, y)^T = \vec{x}$ )

$$
f = \vec{\mathbf{x}}^T P \vec{\mathbf{x}} = \vec{\mathbf{x}}^T Q^T \cdot Q \vec{\mathbf{x}} = (Q \vec{\mathbf{x}})^T \cdot (Q \vec{\mathbf{x}}).
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# **Semi-definite programming**

- $\blacktriangleright$  optimise linear functional
- ▶ on a polytope intersected with the cone of SPD matrices (spectrahedron)
- ▶ weak duality, non-unique solutions
- ▶ even feasibility is a hard problem!

# **SDP problem formulation**

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tries to maximise  $\lambda$  as long as  $(2x^2 + 4x + 1) - \lambda \ge 0$ .

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## **Theorem (Schmüdgen)**

*For any* ∗*-invariant element ξ* ∈ R*[G]*

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\xi \geq 0 \iff \xi + \epsilon u \in \Sigma^2 \mathbb{R}[G]
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for all  $\varepsilon > 0$ , where **u** is an interior point of  $\Sigma^2 \mathbb{R}[\mathsf{G}]$ .

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This of no use for us: SOS decompositions  $\Delta^2 - \lambda \Delta + \varepsilon = \sum \xi_i^* \xi_i$  may be very diffrent for different *ε*.

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If we can show that  $Δ^2 - λΔ + ε₀Δ = ∑ ξ<sup>*</sup><sub>i</sub> ξ<sub>i</sub>$  for a single fixed  $ε₀$ , then

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for all *ε* simultanuously!

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- 2. Set  $\vec{x} = (e, g_1, g_2, \dots, g_n), \quad g_i \in B_d(e, S)$   $(d = 2, 3, \dots);$

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- 2. Set  $\vec{x} = (e, g_1, g_2, \dots, g_n), \quad g_i \in B_d(e, S)$   $(d = 2, 3, \dots);$
- 3. Solve the problem (numerically):

maximize: 
$$
\lambda
$$
  
\nsubject to:  $P \ge 0$ ,  $P \in M_{\vec{x}}$   
\n $\lambda \ge 0$   
\n $(\Delta^2 - \lambda \Delta)_t = \sum_{g^{-1}h=t} P_{g,h}$ , for all  $t \in B_{2d}(e, S)$ 

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4. Compute  $\sqrt{P} = Q = [\overrightarrow{q_e}, \dots, \overrightarrow{q_{g_n}}]$ 5. Finally:  $\xi_g = \langle \vec{\mathbf{x}}, \vec{q_g} \rangle$  and  $\Delta^2 - \lambda \Delta = \sum_{g \in \vec{\mathbf{x}}} \xi_g * \xi_g$ . *How do we certify that the numerical result is sound?*

#### **Lemma (Netzer&Thom)**

*Let*  $r$  ∈ *I*[ $G$ ] ⊂  $\mathbb{R}[G]$  *such that* supp $(r)$  ⊂  $B_d$  $(e)$ *. Then* 

 $r + 2^{d-1} \|r\|_1 \cdot \Delta \in \Sigma^2 I[G].$ 

#### **Corollary**

*If*  $\Delta^2 - \lambda \Delta = \sum \xi_i^* \xi_i + r$ *, then* 

$$
\Delta^2 - \left(\lambda - 2^{d-1} ||r||_1\right) \Delta = \sum \xi_i^* \xi_i + \left(r + 2^{d-1} ||r||_1 \Delta\right) \in \Sigma^2 I[G],
$$

*i.e.*  $\Delta$  *has spectral gap of at least*  $\lambda - 2^{d-1} ||r||_1$ .

1. Pick  $G = \langle S | \mathcal{R} \rangle$ ;

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\n $\lambda \ge 0$   
\n $(\Delta^2 - \lambda \Delta)_t = (\vec{x} P \vec{x}^T)_t$ , for all  $t \in B_{2d}(e, S)$ 

4. Compute 
$$
Q = [\vec{q_e}, \dots, \vec{q_{g_n}}] \sim \sqrt{P}
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1. Pick  $G = \langle S | \mathcal{R} \rangle$ ;

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3. Solve the problem (numerically):

maximize: 
$$
\lambda
$$
  
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\n $\lambda \ge 0$   
\n $(\Delta^2 - \lambda \Delta)_t = (\vec{x} P \vec{x}^T)_t$ , for all  $t \in B_{2d}(e, S)$ 

4. Compute 
$$
Q = [\vec{q_e}, \dots, \vec{q_{g_n}}] \sim \sqrt{P}
$$

5. Setting 
$$
\xi_g = \langle \vec{x}, \vec{q}_g \rangle
$$
 we have  
\n
$$
\Delta^2 - \lambda \Delta = \sum \xi_g^* \xi_g + r, \quad \text{where } r \in I[G] \text{ and } ||r||_1 < \varepsilon.
$$

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$$
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$$

\n- 5. Setting 
$$
\xi_g = \langle \vec{x}, \vec{q_g} \rangle
$$
 we have  $\Delta^2 - \lambda \Delta = \sum \xi_g * \xi_g + r$ , where  $r \in I[G]$  and  $||r||_1 < \varepsilon$ .
\n- 6. Finally  $\Delta^2 - (\lambda - 2^{d-1}\varepsilon)\Delta = \sum \xi_j^* \xi_j + (r + 2^{d-1}\varepsilon)\Delta \geq 0$ , hence  $\lambda_1(G, S) \geq (\lambda - 2^{d-1}\varepsilon)$  is certified.
\n

1. Pick  $G = \langle S | \mathcal{R} \rangle$ :

2. Set  $\vec{x} = (e, q_1, q_2, \dots, q_n), \quad q_i \in B_d(e, S)$   $(d = 2, 3, \dots);$ 

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4. Compute  $Q = [\overrightarrow{q_e}, \dots, \overrightarrow{q_{g_n}}] \sim \sqrt{P}$  $P \rightarrow \sqrt{P} \rightarrow \sqrt{P}_{int} \rightarrow \sqrt{P}$  $\overline{P}_{int}^{aug} \rightarrow Q \in M_{\vec{x}}(\mathbb{R}^d)$ 5. Setting  $\xi_g = \langle \vec{\mathbf{x}}, \vec{q}_g \rangle$  we have  $\Delta^2 - \lambda \Delta = \sum \xi_g^* \xi_g + r$ , where  $r \in I[G]$  and  $||r||_1 < \varepsilon$ . 6. Finally Δ<sup>2</sup> − (λ − 2<sup>d−1</sup>ε)Δ =  $\sum \xi_j^* \xi_j + (r + 2^{d-1} εΔ) ≥ 0$ , hence  $\lambda_1$ (*G*, **S**) ≥ ( $\lambda$  − 2<sup>*d*−1</sup>**ε**) is certified.

## <span id="page-69-0"></span>**[Concrete examples](#page-69-0)**



 $\sqrt{P}$  = *Q* ∈ M<sub>*x*</sub>, where  $\vec{x}$  = *B*<sub>2</sub>(*e*, *E*(3)), i.e. rows and columns are indexed by elements in  $(SL(3, \mathbb{Z}), E(3))$  of word length  $\leq 2$ . In this case

$$
\Delta^2 - 0.28\Delta = \sum_{i=1}^{121} \xi_i^* \xi_i + r, \qquad ||r||_1 \in [3.8508, 3.8511] \cdot 10^{-7}
$$




(after weeks of computation)





 $\blacktriangleright$  Find a finite group  $K < Aut(SAut(F_n))$  which keeps the generating set *S* and (thus)  $\Delta^2 - \lambda \Delta$  invariant ( $K = \mathbb{Z}_2 \wr S_5$ );



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- $\blacktriangleright$  Decompose  $B_{2d}(e, S)$  into orbits of *K* (7229 of them)
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- $\blacktriangleright$  Decompose  $B_{2d}(e, S)$  into orbits of *K* (7229 of them)
- $\blacktriangleright$  Decompose  $B_d(e, S)$  into irreducible representations of *K*
- ▶ Using minimal projection system for *K* reduce the size of the optimisation problem (29 semidefinite constraints, 13233 variables)



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- $\blacktriangleright$  The optimisation problem for  $\lambda$  has a *K*-invariant solution
- $\blacktriangleright$  Decompose  $B_{2d}(e, S)$  into orbits of *K* (7229 of them)
- *Decompose*  $B_d$  (*e, S*) into irreducible representations of *K*
- ▶ Using minimal projection system for *K* reduce the size of the optimisation problem (29 semidefinite constraints, 13233 variables)
- ▶ Solve the smaller problem and reconstruct the solution *P* of the larger one.





## **Bibliography**

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[...] certain things first became clear to me by a mechan*ical method, although they had to be proved by geometry afterwards [...] But it is of course easier, when we have previously acquired, by the method, some knowledge of the questions, to supply the proof than it is to nd it without any previous knowledge.*

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(*The Method of Mechanical Theorems*, Archimedes)