## SAut(F<sub>5</sub>) HAS PROPERTY (T)

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### Outline

Group Laplacians & Property (T) Positivity & SDP The procedure Concrete examples •  $G = \langle S | R \rangle$  is a finitely presented group generated by a fixed **symmetric** generating set (i.e.  $S^{-1} = S$ ).

### **GROUP LAPLACIANS**

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- $\blacktriangleright$  the second eigenvalue  $\lambda_1$  is called the **spectral gap**

$$0 = \lambda_0 \leqslant \lambda_1 \leqslant \cdots$$

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$$\mathcal{H}^{\pi} = \{ \mathsf{v} \in \mathcal{H} : \pi(g)\mathsf{v} = \mathsf{v} \text{ for all } g \in \mathsf{G} \}$$

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### Definition

The **Kazhdan's constant**  $\kappa(G, S)$  is defined as

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over all orthogonal representations  $\pi$  of G. We say that G has the **Kazhdan's property (T)** if and only if there exists a (finite) generating set S such that  $\kappa(G,S) > 0$ .

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- ► SAut(F<sub>3</sub>) does not have (T)... (McCool 1989);
- Does SAut(F<sub>n</sub>) have property (T) for n ≥ 4? (Serre 70s, Lubotzky 1994, Lubotzky-Pak 2001, Fisher 2006, Bridson-Vogtmann 2006, Breuillard 2014, and many more);

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- Provide a constructive (computable) proof for n = 5.

Random group elements in finite groups:

#### Theorem (Lubotzky & Pak, 2000)

Let *K* be a finite group generated by  $k \le n$  elements. If  $SAut(F_n)$  has property (T) with constant  $\kappa = \kappa(SAut(F_n), \{transvections\}) > 0$ , then **PRA** walk on  $\Gamma_n = \Gamma_n(K)$  has fast mixing rate, i.e.

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$$\left\| \left| Q_{(g)}^{t} - U \right| \right\|_{tv} \leq \varepsilon \qquad for \qquad t \geq \frac{16}{\kappa^{2}} \log \frac{|\Gamma_{n}|}{\varepsilon} \sim O\left( \left( \frac{n}{\kappa} \right)^{2} \log \frac{|K|}{\varepsilon} \right)$$

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#### Note

We do observe fast mixing rate in practice for large *n*.

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#### Corollary

Let  $G = \langle S | \dots \rangle$  be a finitely generated group. If there exists  $\lambda > 0$  such that  $\Delta^2 - \lambda \Delta \ge 0$ , then G has property (T) with

$$\sqrt{\frac{2\lambda}{|\mathsf{S}|}} \leqslant \kappa(\mathsf{G},\mathsf{S}).$$

# How to prove that $\Delta^2-\lambda\Delta \geqslant 0$ ?

## How to prove that a polynomial $f \ge 0$ ?

### **POSITIVITY & SDP**

### Theorem (Hilbert's Positivstellensatz, 1888)

An everywhere non-negative polynomial  $p \in \Sigma^2 \mathbb{R}[x_1, ..., x_n]$  (is a sum of squares) if and only if either

- ▶ *n* = 1, or
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 $x^4y^2 + x^2y^2 - 3x^2y^2 + 1 \ge 0$  is SOS if You multiply is by  $x^2 + y^2 + 1$ .

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By evaluating

$$f(x,y) = (1,x,y) \begin{bmatrix} p_{11} & p_{12} & p_{13} \\ p_{21} & p_{22} & p_{23} \\ p_{31} & p_{32} & p_{33} \end{bmatrix} \begin{pmatrix} 1 \\ x \\ y \end{pmatrix}$$

we can obtain any polynomial of degree 2 in x and y with coefficients linear functions of  $p_{ij}$ .

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For **f** to be a SOS we just need  $(p_{ij}) = P$  to be **semi-positive definite**,

since then  $P = Q^T Q$  and (for  $(1, x, y)^T = \vec{x}$ )

$$f = \vec{\mathbf{x}}^{\mathsf{T}} P \, \vec{\mathbf{x}} = \vec{\mathbf{x}}^{\mathsf{T}} Q^{\mathsf{T}} \cdot Q \vec{\mathbf{x}} = (Q \vec{\mathbf{x}})^{\mathsf{T}} \cdot (Q \vec{\mathbf{x}}) \, .$$

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## Semi-definite programming

- ► optimise linear functional
- on a polytope intersected with the cone of SPD matrices (spectrahedron)
- weak duality, non-unique solutions
- even feasibility is a hard problem!

# SDP problem formulation

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tries to maximise  $\lambda$  as long as  $(2x^2 + 4x + 1) - \lambda \ge 0$ .

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For any \*-invariant element  $\xi \in \mathbb{R}[G]$ 

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for all  $\varepsilon > 0$ , where **u** is an interior point of  $\Sigma^2 \mathbb{R}[G]$ .

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This of no use for us: SOS decompositions  $\Delta^2 - \lambda \Delta + \varepsilon = \sum \xi_i^* \xi_i$  may be very different for different  $\varepsilon$ .

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#### **Example**

If we can show that  $\Delta^2 - \lambda \Delta + \varepsilon_0 \Delta = \sum \xi_i^* \xi_i$  for a single fixed  $\varepsilon_0$ , then

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for all  $\varepsilon$  simultanuously!

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$$\begin{array}{ll} \text{maximize:} & \lambda \\ \text{subject to:} & P \geqslant \mathbf{0}, \quad P \in \mathbb{M}_{\vec{x}} \\ & \lambda \geqslant \mathbf{0} \\ & (\Delta^2 - \lambda \Delta)_t = \sum_{g^{-1}h = t} P_{g,h}, \quad \text{for all } t \in B_{2d}(e,S) \end{array}$$

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3. Solve the problem (numerically):

maximize: 
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subject to:  $P \ge 0$ ,  $P \in \mathbb{M}_{\vec{x}}$   
 $\lambda \ge 0$   
 $(\Delta^2 - \lambda \Delta)_t = \sum_{g^{-1}h=t} P_{g,h}$ , for all  $t \in B_{2d}(e, S)$ 

4. Compute  $\sqrt{P} = Q = [\overrightarrow{q_e}, \dots, \overrightarrow{q_{g_n}}]$ 

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How do we certify that the numerical result is sound?

### Lemma (Netzer&Thom)

Let  $r \in I[G] \subset \mathbb{R}[G]$  such that  $supp(r) \subset B_d(e)$ . Then

 $r+2^{d-1}\|r\|_1\cdot\Delta\in\Sigma^2 I[G].$ 

#### Corollary

If  $\Delta^2 - \lambda \Delta = \sum \xi_i^* \xi_i + r$ , then

$$\Delta^2 - \left(\lambda - 2^{d-1} \|r\|_1\right) \Delta = \sum \xi_i^* \xi_i + \left(r + 2^{d-1} \|r\|_1 \Delta\right) \in \Sigma^2 I[G],$$

i.e.  $\Delta$  has spectral gap of at least  $\lambda - 2^{d-1} \|r\|_1$ .

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 $(\Delta^2 - \lambda \Delta)_t = (\vec{x} P \vec{x}^T)_t$ , for all  $t \in B_{2d}(e, S)$ 

4. Compute 
$$Q = [\overrightarrow{q_e}, \dots, \overrightarrow{q_{g_n}}] \sim \sqrt{P}$$

5. Setting 
$$\xi_g = \langle \vec{\mathbf{x}}, \vec{q_g} \rangle$$
 we have  
 $\Delta^2 - \lambda \Delta = \sum \xi_g^* \xi_g + r$ , where  $r \in I[G]$  and  $||r||_1 < \varepsilon$ .

1. Pick  $G = \langle S | \mathcal{R} \rangle$ ;

2. Set  $\vec{\mathbf{x}} = (e, g_1, g_2, \dots, g_n), \quad g_i \in B_d(e, S) \ (d = 2, 3, \dots);$ 

maximize: 
$$\lambda$$
  
subject to:  $P \ge 0$ ,  $P \in \mathbb{M}_{\vec{x}}$   
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6. Finally  $\Delta^2 - (\lambda - 2^{d-1}\varepsilon)\Delta = \sum \xi_j^* \xi_j + (r + 2^{d-1}\varepsilon\Delta) \ge 0$ , hence  
 $\lambda_1(G, S) \ge (\lambda - 2^{d-1}\varepsilon)$  is certified.

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3. Solve the problem (numerically):

maximize: 
$$\lambda$$
  
subject to:  $P \ge 0$ ,  $P \in \mathbb{M}_{\vec{x}}$   
 $\lambda \ge 0$   
 $(\Delta^2 - \lambda \Delta)_t = (\vec{x} P \vec{x}^T)_t$ , for all  $t \in B_{2d}(e, S)$ 

4. Compute Q = [q<sub>e</sub>,...,q<sub>gn</sub>] ~ √P P → √P → √P<sub>int</sub> → √P<sub>int</sub> → Q ∈ M<sub>x̃</sub>(ℝIF)
5. Setting ξ<sub>g</sub> = ⟨x̄, q̄g⟩ we have Δ<sup>2</sup> - λΔ = ∑ ξ<sub>g</sub>\*ξ<sub>g</sub> + r, where r ∈ I[G] and ||r||<sub>1</sub> < ε.</li>
6. Finally Δ<sup>2</sup> - (λ - 2<sup>d-1</sup>ε)Δ = ∑ ξ<sub>j</sub>\*ξ<sub>j</sub> + (r + 2<sup>d-1</sup>εΔ) ≥ 0, hence λ<sub>1</sub>(G,S) ≥ (λ - 2<sup>d-1</sup>ε) is certified.

# **CONCRETE EXAMPLES**



 $\sqrt{P} = Q \in \mathbb{M}_{\vec{x}}$ , where  $\vec{x} = B_2(e, E(3))$ , i.e. rows and columns are indexed by elements in  $(SL(3, \mathbb{Z}), E(3))$  of word length  $\leq 2$ . In this case

$$\Delta^2 - 0.28\Delta = \sum_{i=1}^{121} \xi_i^* \xi_i + r, \qquad \|r\|_1 \in [3.8508, 3.8511] \cdot 10^{-7}$$

G	n	т	λ	$  r  _{1} <$	lbκ	< <i>K</i>	ub <sub>κ</sub>
SL(3,ℤ)	390,287	935,021	0.5405	$5.2 \cdot 10^{-7}$	0.19	0.30014	0.81650
$SL(4,\mathbb{Z})$	93,962	263,122	1.3150	$5.2 \cdot 10^{-8}$	0.00106	0.33103	0.70711
$SL(5,\mathbb{Z})$	628,882	1,757,466	2.6500	$2.0\cdot10^{-4}$	0.00105	0.36400	0.63246
G	n	т	λ	$  r  _{1} <$			
-------------	-----------	-----------	--------	---------------			
$SAut(F_4)$	3,157,730	1,777,542	0.0100	7.4			

(after weeks of computation)

G	n	т
$SAut(F_5)$	21,538,881	11,154,301

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Find a finite group  $K < \operatorname{Aut}(\operatorname{SAut}(F_n))$  which keeps the generating set S and (thus)  $\Delta^2 - \lambda \Delta$  invariant ( $K = \mathbb{Z}_2 \wr S_5$ );

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- Decompose  $B_{2d}(e, S)$  into orbits of K (7229 of them)
- ► Decompose *B*<sub>d</sub>(*e*, *S*) into irreducible representations of *K*
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- The optimisation problem for  $\lambda$  has a *K*-invariant solution
- ▶ Decompose *B*<sub>2d</sub>(*e*, *S*) into orbits of *K* (7229 of them)
- ▶ Decompose *B*<sub>d</sub>(*e*, *S*) into irreducible representations of *K*
- Using minimal projection system for K reduce the size of the optimisation problem (29 semidefinite constraints, 13233 variables)
- Solve the smaller problem and reconstruct the solution *P* of the larger one.



G	n	т	λ	$  r  _{1} <$	< <i>K</i>
$SAut(F_5)$	13,233	7,230	1.3000	$2.1 \cdot 10^{-6}$	0.18028

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[...] certain things first became clear to me by a mechanical method, although they had to be proved by geometry afterwards [...] But it is of course easier, when we have previously acquired, by the method, some knowledge of the questions, to supply the proof than it is to find it without any previous knowledge. [...] certain things first became clear to me by a mechanical method, although they had to be proved by geometry afterwards [...] But it is of course easier, when we have previously acquired, by the method, some knowledge of the questions, to supply the proof than it is to find it without any previous knowledge.

(The Method of Mechanical Theorems, Archimedes)